

## MSP - Microsemi SmartFusion2 Programming

This course describe the Microcontroller Subsystem (MSS) of SmartFusion2 Microsemi Microchip FPGAs

### Objective

- Get an Overview on the Cortex-M Architecture
- Understand the Cortex-M Software implementation and debug
- The Microsemi Implementation and Embedded Development Kit (EDK) with Libero SoC and software Integrated Development environment (IDE) tools are described to create a hardware platform and the software to execute to programme it
- Describe SmartFusion MSS Architecture, I/Os and understand the SmartFusion2 FPGA Fabric Interface
- Become familiar with the MSS Peripherals

### Prerequisites

- Basic knowledge of processor and FPGA technology
- Knowledge of VHDL and C languages

### Course environment

- Microsemi LiberoSoC v12.0 and SoftConsole v6.0
- SmartFusion2 based board

### Plan

#### First Day

#### **Libero SoC**

- Microsemi FPGA & SoC overview
- Libero SoC overview
- Create and Design
- Constraint management
- TestBench and Simulations
- Programme and Debug
- Microsemi tool's

*Exercice : Creating a Libero Project for Firmware*

*Exercice : Libero Project and SoftConsole*

## Cortex-M3 Architecture Overview

- V7-M Architecture Overview
- Core Architecture
  - Harvard Architecture, I-Code, D-Code and System Bus
  - Write Buffer
  - Registers (Two stack pointers)
  - States
  - Different Running-mode and Privileged Levels
  - System Control Block
  - SysTick Timer
  - MPU Overview
- Programming
  - Alignment and Endianness
  - CMSIS Library
- Exception/ Interrupts Mechanism Overview
  - Vector Table
  - Interrupt entry and return Overview
  - Tail-Chaining
  - Pre-emption (Nesting)
  - NVIC Integrated Interrupt Controller
  - Exception Priority Management
  - Fault escalation
  - Debug Interface

## Second Day

### SmartFusion2 Cortex-M3 Processor

- System Level Interface
- Integrated Configurable Debug
- Cortex-M3 Processor Core Peripherals
  - Nested Vectored Interrupt Controller
  - System Control Block
  - System Timer
  - Memory Protection Unit
- Cortex-M3 Processor Description
  - Programmers Model
  - Memory Model
  - Exception Model
  - Fault Handling
  - Power Management
- Cortex-M3 Processor Instruction Set
  - CMSIS Functions
  - Memory Access Instructions
  - General Data Processing Instructions
  - Saturating Instructions
  - Branch and Control Instructions
- Cortex-M3 Processor Peripherals
  - System Control Block
  - System Timer (SysTick)
  - Memory Protection Unit

*Exercice : Cortex-M3 Mode Privilege*

*Exercice : Cortex-M3 Exception Management*

*Exercice : Cortex-M3 MPU*

*Exercice : Cortex-M3 Real-Time Operating System (FreeRTOS)*

## **MSS Cache Controller**

- Cache Matrix
- Memory Mapping
- Memory Maps and Transaction Mapping
- Cache Locked Mode
- How to use cache Controller

*Exercise : Cache Controller Configuration*

## **Embedded NVM (eNVM) and SRAM (eSRAM) Controllers**

- Functional Description
- Security
- How to use eNVM
- SYSREG Control Registers

## **High Performance DMA Peripheral and Controller**

- DMA Controller Initialization
- DMA Controller Operations
- How to use HPDMA
- HDMA Controller Register Map
- Peripheral DMA Architecture Overview
- How to use PDMA
- PDMA Register Map

## **Fabric Interface Controller**

- Architecture Overview
- Functional Description
- AHB-Lite Options
- Implementation Considerations
- How to Use FIC

## **Third Day**

## **Reset Controller**

- Power-On Reset Generation Sequence
- Power-Up to functional Time Data
- CoreResetP Soft Reset Controller
  - Reset Topology
  - Implementation
- How to use the Reset Controller

## **AHB - Advanced High Performance Bus**

- Centralized address decoding
- Address gating logic
- Address pipelining
- Sequential transfers
- AHB-Lite Specification

## Connectivity and Communication

- Universal Serial Bus OTG Controller
- Ethernet MAC
- CAN Controller
- MMUART Peripherals
- Serial Peripheral Interface Controller (SPI)
- Inter-Integrated Circuit Peripherals (I<sup>2</sup>C)
- MSS GPIO
- Communication Block
  - Architecture Overview
  - CoreSysServices Soft IP
  - How to use the communication block
- Real-Time Controller
- System Timer
- Watchdog Timer
- ECC System Service

*Exercice : Programming using UART interface*

*Exercice : MSS CAN drivers and APIs*

*Exercice : Programming using USB OTG Controller Interface*

*Exercice : Using ECC System Service*

*Exercice : FreeRTOS and LWIP Project*

## Renseignements pratiques

**Durée : 3 jours**

**Prix : 0 € HT**