ac6

FD1 - DSP568XX implementation

This course covers the 568XX 16-bit DSP NXP family

Objectives

- The course explains how to design a 56807 based board.
- Optimized coding examples are described.
- A generic interrupt handler is introduced.
- The course focuses on motor driving.
- Practical exercices are executed on a 56807 board.

- This course has been delivered several times to companies developing electric engines.

A lot of programming examples have been developed by ACSYS to explain how to write optimized code.
- *They have been developed with CodeWarrior compiler and are executed under CodeWarrior debugger.*

A more detailed course description is available on request at training@ac6-training.com

Prerequisites

- Basic knowledge about signal processing and motor control.
- Knowledge of CAN bus is recommended, see our course reference CAN bus, reference IA1 - CAN buscourse

Course Environment

- Theoretical course
  - PDF course material (in English) supplemented by a printed version for face-to-face courses.
  - Online courses are dispensed using the Teams video-conferencing system.
  - The trainer answers trainees' questions during the training and provide technical and pedagogical assistance.
- At the start of each session the trainer will interact with the trainees to ensure the course fits their expectations and correct if needed

Target Audience

- Any embedded systems engineer or technician with the above prerequisites.

Evaluation modalities

- The prerequisites indicated above are assessed before the training by the technical supervision of the traineein his company, or by the trainee himself in the exceptional case of an individual trainee.
- Trainee progress is assessed by quizzes offered at the end of various sections to verify that the trainees have assimilated the points presented
- At the end of the training, each trainee receives a certificate attesting that they have successfully completed the course.
  - In the event of a problem, discovered during the course, due to a lack of prerequisites by the trainee a different or additional training is offered to them, generally to reinforce their prerequisites,in agreement with their company manager if applicable.

Plan

INTRODUCTION TO DIGITAL SIGNAL PROCESSING

- Arithmetic processing of real-time signals
- Filtering, convolution, correlation
- Modified dual Harvard architecture
- DSP 568XX family introduction, compatibility with 5600X DSPs
- Introduction of motor types

568XX ARCHITECTURE

- Core buses
- Processing states
- Reset, low voltage, stop and wait operations
- 56807 mapping

THE DSP CORE

- The Data ALU
- The Address Generation Unit
- The Program Control Unit
- The instruction set
- C-to-assembly interface
- Software techniques
- Exception management
- The interrupt routing performed by the ICTN
- The debugging support
- JTAG use to access the OnCE
- The embedded flash memory
- Program sequence
- Erase sequence

HARDWARE IMPLEMENTATION

- On chip clock synthesis
- Wait state X data memory
- Wait state program memory

THE QUAD TIMER MODULE

- Timer module pinout
- Operating modes
- OFLAG output signal

THE ADCs

- Timing, pipelining
- Conversion sequence definition
- Synchronization to the PWM
- Optional sample correction

THE QUADRATURE DECODERS

- Quadrature decoders pinout
- Configurable digital filters
- Watchdog timer implementation

THE PULSE WIDTH MODULATORS

- Independent or complementary channel operation
- Deadtime generators
- IFault protection

THE SCI AND THE SPI MODULES

- SCI block diagram, IO signals
- Asynchronous vs synchronous operation modes
- Baud rate selection
- Bootstrap loading from the SCI
- Asynchronous transmit and receive sequences
- SPI synchronous communications basics
- Master vs slave selection
- Polarity selection

THE MSCAN CONTROLLER

- The MSCAN controllers
- Message buffers structure
- ID bit masking
- Arbitration
- Timing and synchronization
- Error management

Renseignements pratiques

Inquiry : 3 days