



## RT2 - MQX Real Time Programming

*Real-time programming applied to the MQX operating system*

### Objectives

- Discover the concepts of real time multitasking
- Understand Real Time constraints
  - Determinism
  - Preemption
  - Interrupts
- Understand the MQX architecture
- Discover the various MQX services and APIs
- Learn how to develop MQX applications
- Learn how to debug MQX applications
- Learn how to use MQX Library (USB, TCP/IP, File System, Embedded GUI)
- Get an overview on Cortex-M4 architecture

### Course environment

- Convenient course material with space for taking notes
- Example code, labs and solutions
- A PC under Windows XP for two trainees
- A NXP Kinetis K60 (Cortex/M4) with CodeWarrior IDE

### Prerequisites

- Familiarity with embedded C concepts and programming
- Basic knowledge of embedded processors

### Environnement du cours

- Cours théorique
  - Support de cours au format PDF (en anglais) et une version imprimée lors des sessions en présentiel
  - Cours dispensé via le système de visioconférence Teams (si à distance)
  - Le formateur répond aux questions des stagiaires en direct pendant la formation et fournit une assistance technique et pédagogique
- Activités pratiques
  - Les activités pratiques représentent de 40% à 50% de la durée du cours
  - Elles permettent de valider ou compléter les connaissances acquises pendant le cours théorique.
  - Exemples de code, exercices et solutions
  - Pour les formations à distance:
    - ▶ Un PC Linux en ligne par stagiaire pour les activités pratiques, avec tous les logiciels nécessaires préinstallés.
    - ▶ Le formateur a accès aux PC en ligne des stagiaires pour l'assistance technique et pédagogique
    - ▶ Certains travaux pratiques peuvent être réalisés entre les sessions et sont vérifiés par le formateur lors de la session suivante.
  - Pour les formations en présentiel:
    - ▶ Un PC (Linux ou Windows) pour les activités pratiques avec, si approprié, une carte cible embarquée.
    - ▶ Un PC par binôme de stagiaires s'il y a plus de 6 stagiaires.
  - Pour les formations sur site:
    - ▶ Un manuel d'installation est fourni pour permettre de préinstaller les logiciels nécessaires.
    - ▶ Le formateur vient avec les cartes cible nécessaires (et les ramène à la fin de la formation).
- Une machine virtuelle préconfigurée téléchargeable pour refaire les activités pratiques après le cours
- Au début de chaque session (demi-journée en présentiel) une période est réservée à une interaction avec les stagiaires pour s'assurer que le cours répond à leurs attentes et l'adapter si nécessaire

## Audience visée

- Tout ingénieur ou technicien en systèmes embarqués possédant les prérequis ci-dessus.

# Course Outline

## First day

### MQX at a Glance

- MQX overview
- Organization of MQX
- MQX directory structure
  - RTOS directory
  - PSP, BSP, I/O and others source subdirectories
- Initializing and starting MQX
- Developing with NXP CodeWarrior Development Studio
  - Build projects
  - PSP build-project
  - BSP build-project
  - Post-build processing

**Exercise :** Creating a simple MQX (only one task) project using NXP CodeWarrior Development Studio

### Introduction to Real Time

- Base real time concepts
- The Real Time constraints
- Multi-task and real time

### Thread safe data structures

- Need for specific data structures
- Thread safe data structures
  - Linked lists
  - Circular lists
  - FIFOs
  - Stacks
- Data structures integrity proofs
  - Assertions
  - Pre and post-conditions

**Exercise :** Build a general purpose thread safe doubly linked list

## Second day

### Memory Management

- Memory management algorithms
  - Buddy System
  - Best fit
  - First Fit
  - Pools Management
- Understand how MQX RTOS Manages Memory
  - Memory with variable-size blocks
  - Lightweight memory with variable-size blocks

- Memory with fixed-size blocks
- Creating partitions
- Allocating and freeing partition blocks
- Memory management errors
- Stack monitoring
- Controlling caches and MMU Overview (not present on K60 MCU)

**Exercise :** Write a simple, thread safe, buddy system memory manager

**Exercise :** Write a generic, multi-level, memory manager

**Exercise :** Enhance the memory manager for memory error detection

**Exercise :** Detect stack overflow

## Element of a real time system

- Tasks and Task Descriptors
  - Content of the task descriptor
  - List of task descriptors
- Context Switch
- Task Scheduling and Preemption
  - Tick based or tickless scheduling
- Scheduling systems and schedulability proof
  - Fixed priorities scheduling
  - RMA and EDF scheduling

## Managing and Scheduling tasks with MQX

- Managing Tasks
  - Creating tasks
  - Managing task errors
  - Terminating tasks
- Scheduling
  - FIFO scheduling
  - Round Robin scheduling

**Exercise :** Creating your first multi-task project

## Third day

### Timing with MQX RTOS

- Time components
- Timers
- Lightweight timers
- Watchdogs
- Hardware Timer on Cortex-M4

**Exercise :** Turn a LED on and off using software timers

### Interrupt Management in Real Time Systems

- Need for interrupts in a real time system
  - Software Interrupt
  - Time Interrupts
  - Device Interrupts
- Level or Edge interrupts
- Hardware and Software acknowledge
- Interrupt vectoring
- Interrupts and scheduling
- Handling Interrupts and Exceptions in MQX RTOS
  - Initializing interrupt handling

- Restrictions on ISRs
  - Handling exceptions
  - Handling ISR exceptions
  - Handling task exceptions
  - Handling Interrupts on Cortex-M4
- Exercise :** Synchronize Interrupts with tasks

## Synchronization Primitives (1/2)

- Waiting and waking up tasks
- Semaphores
- Events
- Semaphores and Events through MQX RTOS
  - Events
  - Lightweight events
  - Lightweight semaphores
  - Semaphores

**Exercise :** Synchronizing a task with another

## Fourth day

## Synchronization Primitives (2/2)

- Mutual Exclusion
  - Spinlocks and interrupt masking
  - Mutex or Semaphore
  - Recursive or not recursive mutexes
  - Priority inversion problem
  - Priority inheritance (the automatic answer)
  - Priority ceiling (the design centric answer)
- Mutexes and condition variables
- Mutual Exclusion through MQX RTOS
  - Priority inversion
  - Priority inheritance
  - Priority protection
  - Mutexes
- Mailboxes
- Using Mailboxes through MQX RTOS
  - Messages
  - Queues
  - Task Queues

**Exercise :** Implement mutual exclusion between two tasks

**Exercise :** Synchronizing tasks using queues

## Parallelism Problems Solution

- Parallel programming problems
  - Uncontrolled parallel access
  - Deadlocks
  - Livelocks
  - Starvation

**Exercise :** The producer-consumer problem, illustrating (and avoiding) concurrent access problems

**Exercise :** The philosophers dinner problem, illustrating (and avoiding) deadlock, livelock and starvation

## Debugging the application

- Instrumentation

- Logs
- Lightweight logs
- Kernel logs
- Stack usage utilities
- Run-Time Testing
- Embedded Debug

**Exercise :** Debug an application with the log component

## Fifth day

### Developing a New BSP

- Selecting a Baseline BSP
- Modifying Source Code

### USB Library

- USB Host/Device Library Description
- USB Host/Device Stack Directory Structure
- USB Host and USB Device APIs Overview

**Exercise :** Run a NXP USB HID Example

### File System (MFS) Library

- MFS at a Glance
- MFS API Overview

**Exercise :** Use of MFS accessing the SPI-connect SD Card

### Shell Library

- Shell Library Overview

### TCP/IP Stack (RTCS) Library

- RTCS Library Overview
- Setting up the RTCS
- Using Sockets
- RTCS API Overview
- RTCS Applications

**Exercise :** Shell Command line providing microprocessor state information Demo

**Exercise :** Simple Web Server Demo

### Embedded GUI Library

- eGUI Library Overview
- Graphic Object Description
- Structure of Project with eGUI
- Driver API Overview

**Exercise :** Embedded GUI Demo